

# Automated design of dynamic programming scheme for RNA folding with pseudoknots

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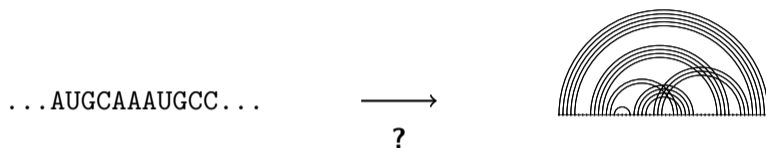
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work to be presented at WABI 2022

## Problem: MFE folding with pseudoknots, from sequence



- ▶ textbook problem: **folding from sequence**
- ▶ without **pseudo-knots**: [RnaFold](#), [mfold](#), [RNAstructure](#)...
- ▶ with PK and a **general energy model**: **NP-hard** [[Sheikh et al., 2012](#), [Lyngsø, 2004](#)]
- ▶ But a variety of polynomial DP algorithms developed for specific cases: [PKnots](#), [NUPACK](#), [gfold](#), [CCJ](#), [Knotty](#)...

## State of the art: DP algorithms for tractable cases

Tool	Reference	space comp.	time comp.	restriction
Pknobs-RE	[Rivas and Eddy, 1999]	$O(n^4)$	$O(n^6)$	“one-hole structures”
NUPACK	[Dirks and Pierce, 2003]	$O(n^4)$	$O(n^5)$	“2 interleaved helices”
gfold	[Reidys et al., 2011]	$O(n^4)$	$O(n^6)$	genus $\leq 1$
CCJ	[Chen et al., 2009]	$O(n^4)$	$O(n^5)$	“3 groups of bands”
Knotty	[Jabbari et al., 2018]	$O(n^3 + Z)$	$O(n^5)$	“CCJ-type + optims”
Pknobs-RG	[Reeder and Giegerich, 2004]	$O(n^2)$	$O(n^4)$	“simple recursive PK”

- ▶ all based on **DP tables indexed by positions on the sequence**
- ▶ designed either with a **specific target structure family** or a **complexity constraint** in mind

## Example of recursive diagram and overall idea

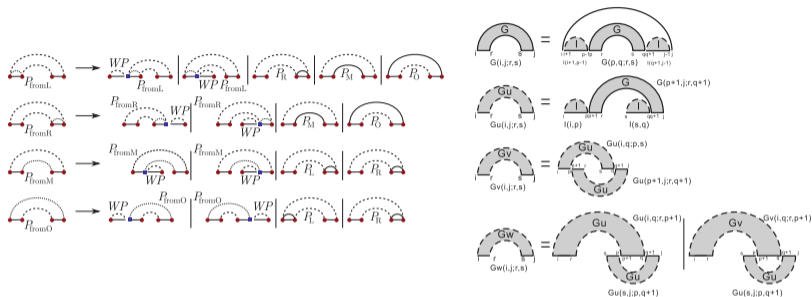
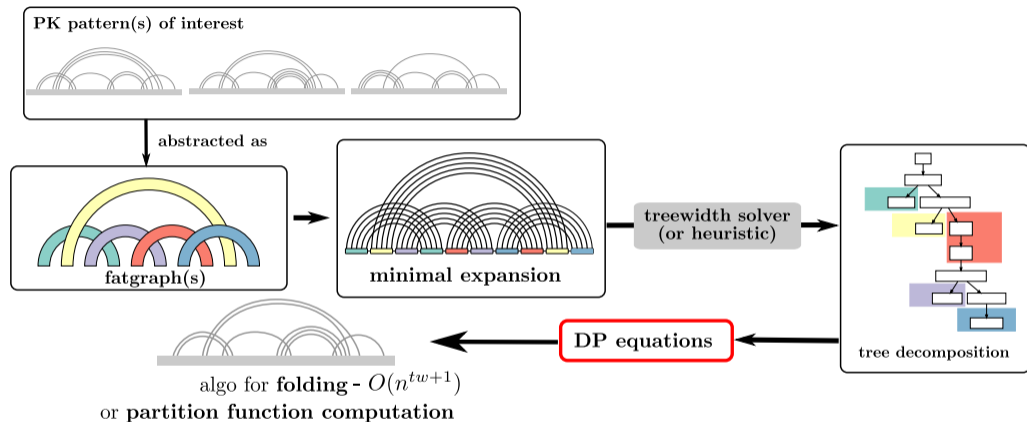


Figure: Examples of DP recursion rules from [Jabbari et al., 2018] and [Reidys et al., 2011]

- Our contribution: a method for, given an **input PK pattern**, **automatically deriving such rules while minimizing the number of used indices**

# Overall pipeline



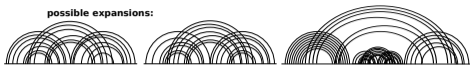
- ▶ **fatgraph:** describes a family of structures following a PK pattern
- ▶ **1 band = 1 helix with arbitrary length/bulges**

## Example: kissing hairpins

- ▶ **Input**, this fatgraph:



possible expansions:



- ▶ **Output** of our program, these equations:

$$A = \min_{a,d,g} (B[a,d|g])$$

$$B'[a,d|d',g] = \min \begin{cases} B[a,d-1|d',g], & \text{if } d-1 \notin \{a,d',g\} \\ B[a+1,d-1|d',g] + \Delta G(a,d) & \text{if } \{a+1,d-1\} \cap \{d',g\} = \emptyset \end{cases}$$

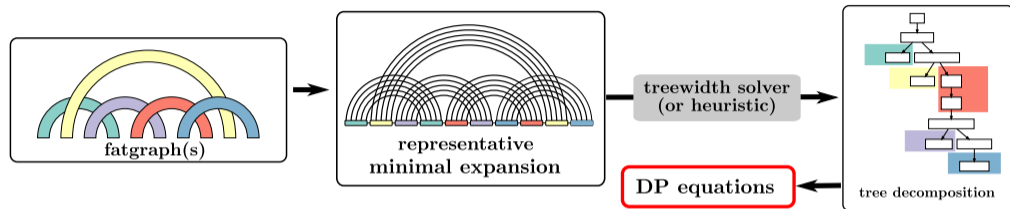
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$$C'[d,g|b,c] = \min \begin{cases} C'[d,g-1|b,c], & \text{if } g-1 \notin \{d,b,c\} \\ C'[d+1,g-1|b,c] + \Delta G(d,g) & \text{if } \{d+1,g-1\} \cap \{b,c\} = \emptyset \end{cases}$$

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- ▶ Output equations **solve folding problem** restricted to the **family of structures** specified by the fatgraph
- ▶ can support **stacking** and **interior loop/bulge energy terms**
- ▶ allow for **recursive substructures**

## Inner engine: tree decompositions



- ▶ **treewidth**: integer quantifying **tree-likeness** of a graph
- ▶ **tree decomposition**: gives you the tree structure
- ▶ we apply it to a **representative** fatgraph expansion
- ▶ essentially gives the **parse tree** of the DP

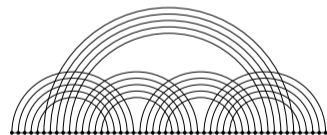
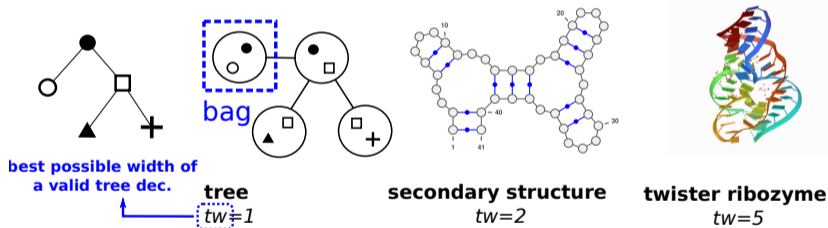


Figure: RNA structure graph

# Tree decomposition: $\sim$ graph parsing tree

Given a graph, **tree of bags** of vertices following:

- ▶ for each **vertex**: **represented** in **connected** set of bags
- ▶ for each **edge**, there is a bag containing both ends
- ▶ **width**: size of **biggest bag** minus one



- ▶ hard to compute in general but good solvers/heuristics
- ▶ **Small** on RNA structures



# Parenthesis: treewidth values of RNAs

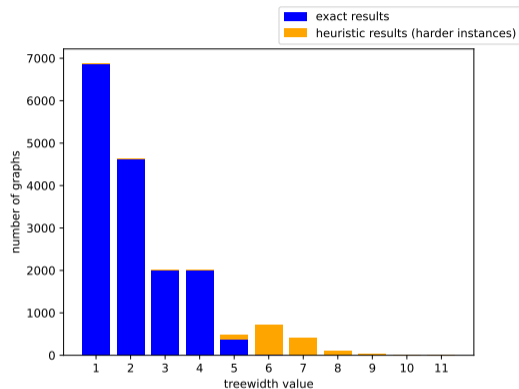


Figure: Canonical interactions only

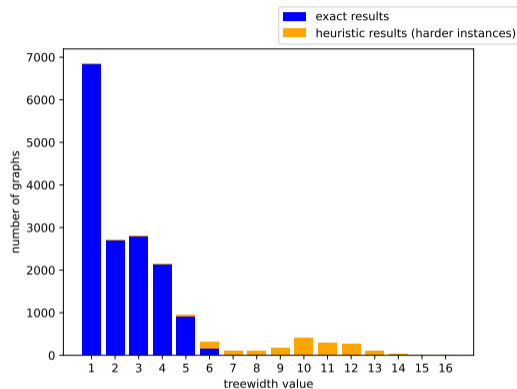


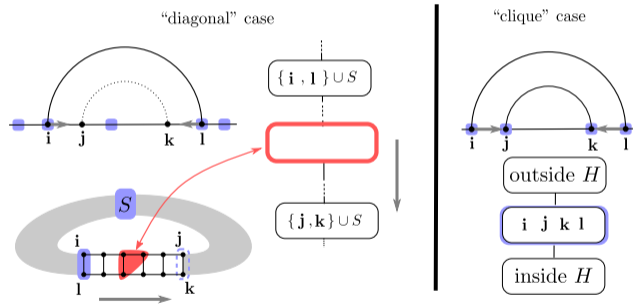
Figure: Including non-canonical interactions

- ▶ Histograms of treewidth values over the PDB database (graph extraction with DSSR)

# Structural results: recovering typical recursion strategies

## Main theorem

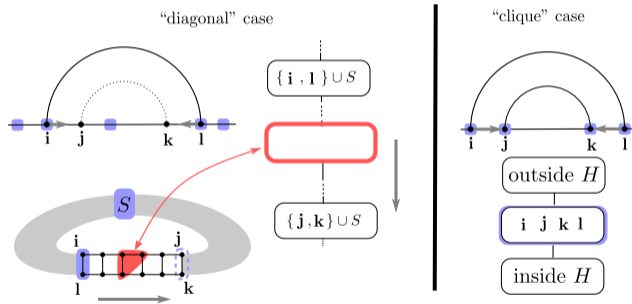
Give an helix  $H$  of **length**  $\geq 5$  in  $G$ , any **tree decomposition** of  $G$  can be modified to represent  $H$  in one of two **canonical ways**



# Structural results: recovering typical recursion strategies

## Main theorem

Give an helix  $H$  of **length**  $\geq 5$  in  $G$ , **any tree decomposition** of  $G$  can be modified to represent  $H$  in one of two **canonical ways**

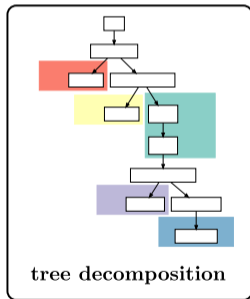


- ▶ + (in our paper) an **algorithm** to re-write tree decompositions for canonical representation

# DP equations from tree decomposition



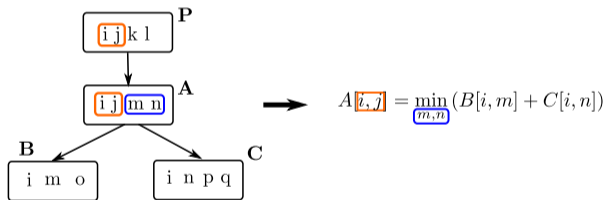
*example fatgraph*



tree decomposition

*canonical tree dec.*

- ▶ One DP table per bag/helix
- ▶ Indices of the table: intersection with parent bag
- ▶ Indices not in parent: marginalization

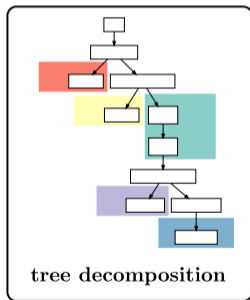


for each table  $\rightarrow$  **number of indices  $\leq$  treewidth**

# DP equations from tree decomposition



*example fatgraph*



**tree decomposition**

*canonical tree dec.*

$$A = \min_{a,g,h,j,k} (B[a, g, h, j] + C_{\boxtimes}[g, h - 1, j, k - 1])$$

$$B[a, g, h, j] = \min_{e,f,i} (C_{\boxtimes}[e, f - 1, h, i - 1] + C[a, e|f, g, i, j])$$

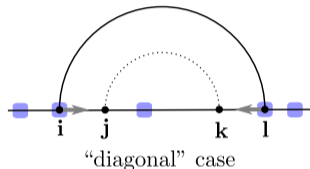
$$C[a, e|f, g, i, j] = \min \begin{cases} C[a + 1, e|f, g, i, j], \\ C[a, e - 1|f, g, i, j], \\ C[a + 1, e - 1|f, g, i, j] + \Delta G(a, e), \\ D[a, e + 1, f, g, i, j] \end{cases}$$

$$D[b, d, f, g, i, j] = \min_c (C_{\boxtimes}[c, d - 1, f, g - 1] + C_{\boxtimes}[b, c - 1, i, j - 1])$$

# Helix equations (for simplicity: ambiguous, Nussinov)

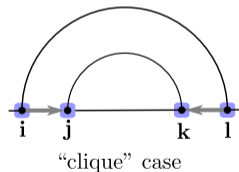
**diag case:** only one end given:

$$D[i, l | S] = \min \begin{cases} D[i + 1, l | S] \\ D[i, l - 1 | S] \\ D[i + 1, l - 1 | S] + \text{score}(i, l) \\ \sum_{c \in \text{children}} M_c[l_c \subset \{i, l\} \cup S] \end{cases}$$

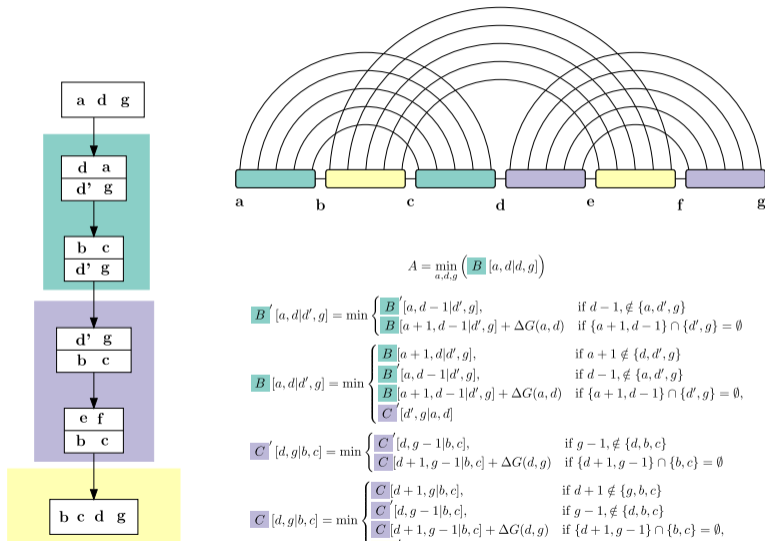


**clique case:** when all 4 extremities are constrained:

$$C_{\boxtimes}[i, j, k, l] = \min \begin{cases} C_{\boxtimes}[i + 1, j, k, l] \\ C_{\boxtimes}[i, j, k, l - 1] \\ C_{\boxtimes}[i + 1, j, k, l - 1] + \text{score}(i, j) \\ 0 \text{ if } (i, l) = (j, k) \end{cases}$$



# Example: kissing hairpins - treewidth=4



$$A = \min_{a,d,g} (B[a,d|d,g])$$








$$B'[a,d|d',g] = \min \begin{cases} B'[a,d-1|d',g], & \text{if } d-1 \notin \{a,d',g\} \\ B[a+1,d-1|d',g] + \Delta G(a,d) & \text{if } \{a+1,d-1\} \cap \{d',g\} = \emptyset \end{cases}$$

$$B[a,d|d',g] = \min \begin{cases} B[a+1,d|d',g], & \text{if } a+1 \notin \{d,d',g\} \\ B[a,d-1|d',g], & \text{if } d-1 \notin \{a,d',g\} \\ B[a+1,d-1|d',g] + \Delta G(a,d) & \text{if } \{a+1,d-1\} \cap \{d',g\} = \emptyset, \\ C[d',g|a,d] \end{cases}$$

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## More examples

Name	fatgraph	treewidth	non-Turner, non-recursive	Turner recursive
H-type		4	$O(n^5)$	$O(n^5)$
kissing hairpins		4	$O(n^4)$	$O(n^5)$
“L”		5	$O(n^6)$	$O(n^6)$
“M”		5	$O(n^6)$	$O(n^6)$
4-clique		5	$O(n^6)$	$O(n^6)$
5-clique		5	$O(n^6)$	$O(n^6)$
5-chain		6	$O(n^7)$	$O(n^7)$

- ▶ first 4 examples: the 4 “shadows” used in gfold [Reidys et al., 2011]  
→ we recover the same complexity automatically



## Features and limitations

- ▶ Can take as input a *finite* number of fatgraphs, with expansions of these fatgraphs recursively inserted.
- ▶ Regular secondary structure can also be inserted recursively
- ▶ Energy model: depends on what is put in the equations of the two helix cases. → stacking terms and bulges/interior-loop with same complexity cost [Lyngsøet al., 1999].
- ▶ Non-ambiguous: partition function computations

### Limitations:

- ▶ Conformational space of some algorithms ([Rivas and Eddy, 1999], [Dirks and Pierce, 2003]) cannot be described with finite number of fatgraphs

## Conclusion and next steps

- ▶ Interestingly → we recover typical DP strategies from graph theory analysis
- ▶ Algorithm generation: 20 seconds on my laptop to generate all examples shown

### Future steps

- ▶ Generate **code** directly (and not just latex)
- ▶ Complexity is “minimized” but could we prove it is optimal in some sense?

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- ▶ In general: my PhD → using treewidth to include pseudoknots into algorithms

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**Thank you**

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